# A Compact Positively Invariant Set of Solutions of the Nagumo Equation 

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## 1. Introduction

The solutions of a parabolic partial differential equation can be considered as a semiflow in some function space. In order to apply the index theory (for example [5]) to study the qualitative behavior of the semiflow, it is often very useful to have a compact positively invariant set which is large enough to contain all intersting solutions (steady state solutions, traveling wave solutions, etc.).

The purpose of this paper is to find a compact positively invariant set of solutions of the Nagumo equation

$$
\begin{align*}
u_{t} & =\alpha v-\beta u \\
v_{t} & =v_{x x}+f(v)-u \tag{1}
\end{align*}
$$

where $u, v$ are real functions in $C^{3}\left(R \times R^{+}\right), \alpha, \beta>0$ and $f \in C^{3}(R)$ satisfying the following conditions:
(i) $f(0)=0$
(ii) $f(-m)>(\alpha / \beta) m, f(m)<-(\alpha / \beta) m$ for large $m$.

We also assume that there exists $K>0$ such that for every fixed $t,|u(x, t)|$ and $|v(x, t)|$ are less than $e^{K x^{2}}$ provided $|x|$ is sufficiently large.

## A Compact Positively Invariant Set

For fixed $t$, we consider a solution $\binom{u}{v}$ of Eq. (1) as a curve $\Gamma^{t}: R \rightarrow R^{4}$ with parameter $x$, and

$$
\Gamma^{t}(x)=\left(\begin{array}{c}
u(x, t) \\
v(x, t) \\
u_{x}(x, t) \\
v_{x}(x, t)
\end{array}\right)
$$

[^0]We find a bounded closed region $B$ in $R^{4}$ (see Fig. 2) such that if $\Gamma^{0}(x) \in B$ for all $x \in R$, then $\Gamma^{t}(x) \in B$ for all $(x, t) \in R \times R^{+}$.

## 2. A Bounded Positively Invariant Set

Definition 1. A positively invariant set $S$ means a subset of $C^{3}(R) \times C^{3}(R)$ such that every solution of Eq. (1) with initial value in $S$ will stay in $S$ for all $t \geqslant 0$.

Definition 2. $\left.\quad S_{1}(m)=\left\{\begin{array}{c}u \\ v \\ v\end{array}\right) \in C^{3}(R) \times C^{3}(R)| | v \right\rvert\, \leqslant m$ and $\left.|u| \leqslant(\alpha / \beta) m\right\}$. For fixed $t$, we consider a solution $\binom{u}{v}$ of Eq. (1) as a curve $\gamma^{t}$ in $R^{2}$ with parameter $x \in R$ and $\gamma^{t}(x)=\binom{u(x, t)}{v(x, t)}$.

Roughly speaking, in the next lemma, we show that if $\gamma^{t}$ is inside the rectangle in Fig. 1, and if it touches the boundary of the rectangle, it will be bounced inward. Therefore, once $\gamma^{t}$ is in the rectangle, it will be trapped forever.


Figure 1

Lemma 3. For sufficiently large $m, S_{1}(m)$ is positively invariant.
Proof. Let $\binom{u}{v}$ be a solution of Eq. (1) with the initial value $\binom{u(x, 0)}{v(x, 0)}$ in $S_{1}(m)$. Assume that for every fixed $t>0,|u(x, t)|,|v(x, t)|$ are less than $e^{K x^{2}}$ for sufficiently large $|\boldsymbol{x}|$.

Let $b=4(K+2)^{2}, a>2(K+2), \epsilon>0$ and $q(x, t)=e^{a t+(b t+K+1) x^{2}}$.

Define two auxiliary functions:

$$
\xi(x, t)=m+\epsilon q(x, t) ; \quad \eta(x, t)=(\alpha / \beta) \xi(x, t) .
$$

It is easy to see that $|u(x, 0)|<\eta(x, 0)$ and $|v(x, 0)|<\xi(x, 0)$; and for every fixed $t$, if $|x|$ is sufficiently large, we have $|u(x, t)|<\eta(x, t)$ and $|v(x, t)|<\xi(x, t)$.

By simple computation, we have

$$
\begin{aligned}
q_{t} & =\left(a+b x^{2}\right) q \text { and } \\
q_{x x} & =\left[4(b t+K+1)^{2} x^{2}+2(b t+K+1)\right] q
\end{aligned}
$$

Let $0<t<1 / b$. Consider the following 4 cases:
(i) If $|u| \leqslant \eta, v=\xi, v_{x}=\xi_{x}$ and $v_{x x} \leqslant \xi_{x x}$, substituting $v_{t}$ by (1), we have $\xi_{t}-v_{t}=\xi_{t}-\left(v_{x x}+f(v)-u\right) \geqslant \xi_{t}-\xi_{x x}-f(\xi)-\eta \geqslant\left[a+b x^{2}-\right.$ $\left.4(b t+K+1)^{2} x^{2}-2(b t+K+1)\right] q-f(\xi)-\alpha / \beta>0$, because $b t<1$, $b=4(K+2)^{2}, a>2(K+2)$ and for sufficiently large $\xi, f(\xi)<-(\alpha / \beta) \xi$.
(ii) If $|u| \leqslant \eta, v=-\xi, v_{x}=-\xi_{x}$ and $v_{x x} \geqslant-\xi_{x x}$, then we have

$$
\begin{aligned}
-\xi_{t}-v_{t} & =-\xi_{t}-\left(v_{x x}+f(v)-u\right) \\
& \leqslant-\xi_{t}+\xi_{x x}-f(-\xi)+(\alpha / \beta) \xi<0
\end{aligned}
$$

(iii) If $|\boldsymbol{v}| \leqslant \xi, u=\eta$, then we have

$$
\begin{aligned}
\eta_{t}-u_{t} & =\eta_{t}-(\alpha v-\beta u) \\
& \geqslant(\alpha / \beta) \epsilon\left(a+b x^{2}\right) q-\alpha \xi+\beta(\alpha / \beta) \xi>0
\end{aligned}
$$

(iv) If $|v| \leqslant \xi, u=-\eta$, then we have

$$
-\eta_{t}-u_{t} \leqslant-(\alpha / \beta) q_{t}+\alpha \xi-\beta \eta<\alpha \xi-\beta(\alpha / \beta) \xi=0 .
$$

Therefore, applying the Nagumo-Westphal lemma for systems of parabolic equations (see [4]), we have $|v(x, t)|<\xi(x, t)$ and $|u(x, t)|<\eta(x, t)$ for $0 \leqslant t<1 / b$.

Since $\epsilon$ can be arbitrarily small we have $|u(x, t)| \leqslant(\alpha / \beta) m$ and

$$
|v(x, t)| \leqslant m \quad \text { for } \quad 0 \leqslant t<1 / b
$$

The above argument can be applied again and again, hence

$$
|u(x, t)| \leqslant(\alpha / \beta) m \quad \text { and } \quad|v(x, t)| \leqslant m \quad \text { for all } \quad t \geqslant 0 .
$$

## 3. A Compact Positively Invariant Set

$S_{1}(m)$ is bounded but not compact. Now we find a positively invariant subset of $S_{1}(m)$ whose elements have uniformly bounded derivatives.

At first we have to develop some technical results.
Consider the autonomous system of ordinary differential equations.

$$
\begin{align*}
d v / d x & =w \\
d w / d x & =-f(v) \mp v w .
\end{align*}
$$

In the $v-w$ phase space, let $\tilde{w}^{+}(v)\left(\tilde{w}^{-}(v)\right)$ be the orbit of the system $\left(2^{+}\right)$ (system (2-)) passing through the point $\tilde{w}^{+}(0)=(\beta / 2 \alpha) n\left(\tilde{w}^{-}(0)=-(\beta / 2 \alpha) n\right.$, respectively), where

$$
\begin{align*}
m_{1} & =\max _{u, v \in S_{1}(m)}\{|u|,|v|,|f(v)|, 1\}  \tag{3}\\
n & =\max \left\{8 m_{1}^{2}(\alpha / \beta), 2 m_{1}^{2}, 32\left(\alpha^{2} / \beta^{2}\right)\right\} . \tag{4}
\end{align*}
$$

Note. The definitions of $\tilde{w}^{ \pm}$, and $m_{1}, n$ will be used throughout this paper.
Lemma 4. $1<\left|\tilde{w}^{ \pm}(v)\right|<(\beta / \alpha) n$ for $|v| \leqslant m_{1}$.
Proof. From Eq. ( $2^{ \pm}$), it follows

$$
\frac{d \tilde{w}^{ \pm}}{d v} \tilde{w}^{ \pm}=-f(v) \mp v \tilde{w}^{ \pm} .
$$

Assuming that $\left|\tilde{w}^{ \pm}\right| \geqslant 1$, and using the above formula and (3), we get

$$
\begin{equation*}
\left|\frac{d \tilde{w}^{ \pm}}{d v}\right| \leqslant\left|\frac{f(v)}{\tilde{w}^{ \pm}}\right|+|v| \leqslant 2 m_{1} . \tag{5}
\end{equation*}
$$

But $\tilde{w}^{ \pm}(v)$ starts at $\left|\tilde{v}^{ \pm}(0)\right|=\frac{1}{2}(\beta / \alpha) n>1$, therefore by (5), if $|v| \leqslant \boldsymbol{m}_{1}$, we have

$$
\left|\tilde{w}^{ \pm}(v)\right| \geqslant \tilde{w}^{ \pm}(0)-\left|\frac{d \tilde{w}^{ \pm}}{d v}\right||v|
$$

using (3), (4), (5)

$$
\begin{align*}
& \geqslant \frac{1}{2}(\beta / \alpha) n-2 m_{1}{ }^{2}  \tag{6}\\
& \geqslant \frac{1}{4}(\beta / \alpha) n>1 .
\end{align*}
$$

So the above assumption is a fact.
Using (5) again and recalling (3), (4), we have

$$
\begin{align*}
\left|\tilde{w}^{ \pm}(v)\right| & \leqslant \tilde{w}^{ \pm}(0)+\left|\frac{d \tilde{w}}{d v}\right||v| \\
& \leqslant \frac{1}{2}(\beta / \alpha) n+2 m_{1}{ }^{2}  \tag{7}\\
& \leqslant \frac{1}{2}(\beta / \alpha) n+\frac{1}{4}(\beta / \alpha) n<(\beta / \alpha) n .
\end{align*}
$$

Thus we have proved the lemma.

Definition 5. $\left.\quad S_{2}(m)=\left\{\begin{array}{l}u \\ v\end{array}\right) \in S_{1}(m)| | u_{x} \right\rvert\,<n$ and $\tilde{w}^{-}(v(x)) \leqslant v_{x}(x) \leqslant$ $\tilde{w}^{+}(v(x))$ for $\left.x \in R\right\}$ (see Fig. 2).

Theorem 6. $\quad S_{2}(m)$ is positively invariant for large $m$.
Bcfore we prove the theorem, we necd to establish some identitics.
Let $\binom{u}{v}$ be a solution of Eq. (1). Set $w=v_{x}, z=u_{x}$. Differentiating Eq. (1) wrt $x$, we get

$$
\begin{align*}
& z_{t}=\alpha w-\beta z  \tag{8}\\
& w_{t}=w_{x x}+f^{\prime}(v) w-z \tag{9}
\end{align*}
$$

When $v_{x} \neq 0$, locally we can consider $z, w$ as functions of $v$ and $t$. Define

$$
\begin{align*}
& \bar{z}(v, t)=\bar{z}(v(x, t), t)=z(x, t),  \tag{10}\\
& \bar{w}(v, t)=\bar{w}(v(x, t), t)=w(x, t) . \tag{11}
\end{align*}
$$

Through a change of variable, Eqs. (8)-(9) can be rewritten as:

$$
\begin{align*}
\bar{z}_{t} & =-\bar{z}_{v} v_{t}+z_{t} \\
& =-\bar{z}_{v}\left(\bar{w}_{v} w+f(v)-u\right)+\alpha \bar{w}-\beta \bar{z} \tag{12}
\end{align*}
$$

and

$$
\begin{align*}
\bar{w}_{t} & =-\bar{w}_{v} v_{t}+w_{t} \\
& =\bar{w}^{2} \bar{w}_{v v}-f(v) \bar{w}_{v}+f^{\prime}(v) \bar{w}-\bar{z}+\bar{w}_{v} u \tag{13}
\end{align*}
$$

These will be needed later.
Now let us consider the ordinary differential equation ( $2^{ \pm}$) which can be written as:

$$
d^{2} v / d x^{2}+f(v)=\mp v w
$$

When $d v / d x \neq 0$, locally we can define:

$$
\begin{equation*}
\hat{w}(v)=\hat{w}(v(x))=w(x) \tag{15}
\end{equation*}
$$

Using ( $14^{ \pm}$), we get the following identity

$$
-\frac{d \hat{w}}{d v}\left(\frac{d^{2} v}{d x^{2}}+f(v)\right)+\frac{d}{d x}\left(\frac{d^{2} v}{d x^{2}}+f(v)\right)=-\frac{d \hat{w}}{d v}(\mp v w)+\frac{d}{d x}(\mp v w),
$$

which can be simplified as:

$$
\hat{w}^{\hat{w}^{2}} \frac{d^{2} \hat{w}}{d v^{2}}+f^{\prime}(v) \hat{w}-f(v) \hat{w}_{v}=\mp \hat{w}^{2}
$$

Proof of Theorem 6. Let $\binom{u}{v}$ be a solution of Eq. (1), $w=v_{x}, z=u_{x}$, $\bar{z}, \bar{w}$ be defined as in (10), (11). For fixed $t$, we consider $\binom{u}{v}$ as a curve $\Gamma^{t}$ in $R^{4}$ by defining

$$
\Gamma^{t}(x)=\left(\begin{array}{c}
u(x, t) \\
v(x, t) \\
u_{x}(x, t) \\
v_{x}(x, t)
\end{array}\right)
$$

Let $B$ be the closed region in $R^{4}$ bounded by $v= \pm m, u= \pm(\alpha / \beta) m, z= \pm n$, $w=\tilde{w}^{+}(v)$, and $w=\tilde{w}^{-}(v)$ (see Fig. 2). We show that if $\Gamma^{t}$ is in $B$ and if it touches the boundary of $B$, it will be bounced inward.


Figure 2

In Lemma 3 we have covered the cases of $\Gamma^{t}$ touching the boundary in $u, v$ directions, so we only need to discuss the following two cases.

Case 1. If $\Gamma^{t}$ touches the $z$ directional boundary at $x=x_{0}$, then $z\left(x_{0}, t\right)=n$ and $z_{x}\left(x_{0}, t\right)=0$. Applying (8) and Lemma 4 we have

$$
\begin{aligned}
z_{t}\left(x_{0}, t\right) & =\alpha w-\beta z \leqslant \alpha\left|\tilde{w}^{ \pm}\right|-\beta z \\
& <\alpha \cdot(\beta / \alpha) n-\beta n \leqslant 0 .
\end{aligned}
$$

Case 2. If $\Gamma^{t}$ touches the $w$ directional boundary at $v=v_{0}$, then we have

$$
\begin{align*}
\bar{w}\left(v_{0}, t\right) & =\tilde{w}^{+}\left(v_{0}\right), \\
\bar{w}_{v}\left(v_{0}, t\right) & =\frac{d \tilde{v}^{+}}{d v}\left(v_{0}\right)
\end{align*}
$$

and

$$
\bar{w}_{v v}\left(v_{0}, t\right) \leqslant \frac{d^{2} \tilde{w}^{+}}{d v^{2}}\left(v_{0}\right)
$$

Using (13), at the point $\left(v_{0}, t\right)$, we have

$$
\begin{aligned}
\bar{w}_{t} & =\bar{w}^{2} \bar{w}_{v v}-f\left(v_{0}\right) \bar{w}_{v}+f^{\prime}\left(v_{0}\right) \bar{w}-\bar{z}+\bar{w}_{v} u \\
& \leqslant\left(\tilde{w}^{+}\right)^{2} \frac{d^{2} \tilde{w}^{+}}{d v^{2}}-f\left(v_{0}\right) \tilde{w}_{v}++f^{\prime}\left(v_{0}\right) \tilde{w}^{+}-\bar{z}+\tilde{w}_{v}+u \quad \text { by (17) } \\
& =-\left(\tilde{w}^{+}\right)^{2}-\bar{z}+\tilde{w}_{v}+u \quad \text { by }(16)
\end{aligned}
$$

using the definition of $B$ and (6), (5), and (3)

$$
\begin{aligned}
& \leqslant-\left(\frac{1}{4}(\beta / \alpha) n\right)^{2}+n+2 m_{1}{ }^{2} \\
& =-\frac{1}{16}\left(\beta^{2} / \alpha^{2}\right) n \cdot n+n+2 m_{1}{ }^{2} \\
& \leqslant-2 n+n+2 m_{1}{ }^{2} \quad \text { by }(4) \\
& \leqslant-n+2 m_{1}{ }^{2}<0 \quad \text { by }(4) .
\end{aligned}
$$

The same argument can be applied to the cases $\Gamma^{t}$ touches $z=-n$ or $w=\tilde{w}(v)$.

Therefore, once $\binom{u}{v}$ is in $S_{2}(m)$, it will stay in $S_{2}(m)$ forever.
Theorem 7. $\quad S_{2}(m)$ is compact wrt c-O topology. (i.e., the topology generated by sup-norms of $u$, v restricted to every bounded interval of the real line.)

Proof. Let $\binom{u}{u} \in S_{2}(m) \cdot u, v, u_{x}, v_{x}$ are uniformly bounded. Hence by Ascoli-Azela Theorem, $S_{2}(m)$ is compact wrt $c-O$ topology.

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