國立政治大學 應用數學系碩士學位論文

一個卡特蘭等式的組合證明

## A Combinatorial Proof of a Catalan Identity

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# 國立政治大學應用數學系 

劉映君君所撰之碩士學位論文
# 一個卡特蘭等式的組合證明 <br> A Combinatorial Proof of a Catalan Identity 

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## 中文摘要

在這篇論文裡，我們探討卡塔蘭等式 $(n+2) C_{n+1}=(4 n+2) C_{2}$ 的證明方法。以往都是用計算的方式來呈現卡塔蘭等式的由來，但我們選擇用組合的方法來證明卡塔蘭等式。

這篇論文主要是應用 $C_{n+1}$ 壞路徑對應到打點 $C_{n}$ 好路徑以及 $C_{n+1}$ 好路徑對應到打點 $C_{n}$ 壞路徑的方式來證明卡特蘭等式

關鍵字：卡塔蘭等式

## Abstract

In this thesis, we give another approach to prove Catalan identity, $(n+2) C_{n+1}=(4 n+2) C_{2}$. In the past we use the method of computation to show Catalan Identity, in this thesis we choose a combinatorial proof of the Catalan identity.

This thesis is primary using the functions from $C_{n+1}$ totally bad path to $C_{n}$ dotted good path, and from $C_{n+1}$ good path to $C_{n}$ dotted totally bad path.

Keywords: Catalan Identity

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## Chapter 1

## Introduction

## 政 治

Definition 1.1. A segment is either an east(e) or a north(n). A path consists of consecutive segments.

Definition 1.2. An $(n, n)$ path is a path with $n$ e's and $n$ n's segments.

Definition 1.3. A good path means that all segments are below diagonal $y=x$. A bad path is a path that is not a good path.

Note : A bad path has at least one segment above diagonal $y=x$.

Definition 1.4. A totally bad path means that all segments are aboye diagonal $y=x$.

Catalan numbers are the number of good paths from the origin to the point $(n, n)$, and we define Catalan number, $C_{n}$, by $C_{n}=\frac{1}{n+1} C_{n}^{2 n}$, for $n \geq 0$. In this thesis, we focus on a combinatorial proof of a Catalan identity,
$(n+2) C_{n+1}=(4 n+2) C_{n} .[6]$

In general, we obtain this formula by

$$
\begin{aligned}
(n+2) C_{n+1} & =\frac{(n+2) C_{n+1}^{2 n+2}}{n+2} \\
& =\frac{(2 n+2)!}{(n+1)!(n+1)!} \\
& =\frac{(2 n+1)(2 n)!(2 n+2)}{(n+1) n!n!(n+1)} \\
& =\frac{2(2 n+1)(2 n)!(2 n+2)}{(n+1) n!n!(2 n+2)} \\
& =\frac{(4 n+2)(2 n)!}{(n+1) n!n!} \\
& =\frac{(4 n+2) C_{n}^{2 n}}{n+1}=(4 n+2) C_{n}
\end{aligned}
$$

It is well-known that the number of paths with $n+1$ flaws, which has $n+1$ east and $n+1$ north segments above the diagonal $y=x$, is equal to the number of such paths with $n$ flaws, which is equal to the number of such paths with $n-1$ flaws, and so on. In other words, we have split up the set of all paths into $n+2$ equally sized classes. Since there are $C_{n+1}^{2 n+2}$ paths, we obtain the desired formula $C_{n+1}=\frac{1}{(n+2)} C_{n+1}^{2 n+2}$. So the left side $(n+2) C_{n+1}=C_{n+1}^{2 n+2}$.
By Pascal Identity, $C_{n+1}^{2 n+2}=0 / \underbrace{C_{n}^{2 n+1}}_{\text {Paths starting with north }}+\underbrace{C_{n+1}^{2 n+1}}_{\text {Paths starting with east }}$
On the right-hand side, $(4 n+2) C_{n}=2(2 n+1) C_{n}=\underbrace{(2 n+1) C_{n}}_{\text {Dotted good paths }}+\underbrace{(2 n+1) C_{n}}_{\text {Dotted totally bad paths }}$. In Chapter 2, we give a bijective proof between "Paths start with north" and "Dotted good paths". In Chapter 3, we give a bijective proof between "Paths start with east" and "Dotted totally bad paths".

Therefore, we complete the proof of $(n+2) C_{n+1}=(4 n+2) C_{n}$ combinatorially.
For more details, we refer to [1-5, 7-10]

## Chapter 2

## Paths Start with North

Definition 2.1. The set $X_{1}$ consists of all $(n+1, n+1)$ paths which have at least one flaw.
Each path in $X_{1}$ can be factorized into $G T \stackrel{\rightharpoonup}{e} Q$. The set $Y_{1}$ consists of all $(n+1, n+1)$ paths which has at most $n$ flaws.

Define a function $f_{1}$ from $X_{1}$ into $Y_{1}$ by the following:

1. Starting from the bottom left, $(0,0)$, follow the path until it first travels above the diagonal $y=x$.
2. Continue to follow the path until it touches the diagonal $y=x$ again. Denote by $\vec{e}$, the first such segment that touches the diagonal $y=x$, in fact, $\vec{e}$ must be an east segment.
3. Swap the portion of the path before $\stackrel{\rightharpoonup}{e}$ with portion after $\stackrel{\rightharpoonup}{e}$.
i.e. $f_{1}(G T \vec{e} Q)=Q \vec{e} G T$,
where $G$ is an $(i, i)$ good path, $0 \leq i \leq n+1, T$ is a $(j, j+1)$ totally bad path, $0 \leq j \leq$ $n-i$, the east segment $\vec{e}$ is the first east which touches the diagonal $y=x$, and $Q$ is an ( $n-i-j, n-i-j$ ) path.

NOTE: After using $f_{1}$, the flaws of path $P$ decrease one.
i.e. If $P$ has k flaws, $k \geq 1$, then $f_{1}(P)$ has $k-1$ flaws.

To show $f_{1}(G T \vec{e} Q)=Q \vec{e} G T$ by graph, we have:


Fix $\vec{e}$ and switch $G T$ with $Q$, we have:


Figure 2.2: $Q \vec{e} G T$

Theorem 2.2. Let $P=G T \vec{e} Q$ is an $(n+1, n+1)$ path. Define $f_{1}: X_{1} \longrightarrow Y_{1}$
by $f_{1}(G T \stackrel{\rightharpoonup}{e} Q)=Q \vec{e} G T$, where $G$ is an $(i, i)$ good path, $0 \leq i \leq n+1, T$ is a $(j, j+1)$ totally bad path, $0 \leq j \leq n-i$, the east segment $\vec{e}$ is the first east which touches the diagonal $y=x$, and $Q$ is an $(n-i-j, n-i-j)$ path. The function $f_{1}$ is one-to-one and onto.

Proof. Claim: $f_{1}$ is one-to-one.
Let $P=G T \stackrel{\rightharpoonup}{e} Q, P^{\prime}=G^{\prime} T^{\prime} \stackrel{\rightharpoonup}{e} Q^{\prime}$, where $T^{\prime}$ is a an $(l, l+1)$ totally bad path, $G^{\prime}$ is a $(k, k)$ good path, and $Q^{\prime}$ is an $(n-k-l, n-k-l)$ path.
$f_{1}(G T \vec{e} Q)=f_{1}\left(G^{\prime} T^{\prime} \stackrel{\rightharpoonup}{e} Q^{\prime}\right) \Rightarrow Q \stackrel{\rightharpoonup}{e} G T=Q^{\prime} \stackrel{\rightharpoonup}{e} G^{\prime} T^{\prime}$.
Claim: $T=T^{\prime}$
Case1: $l>j$


Figure 2.3: $Q \vec{e} G T$


Figure 2.4: $Q^{\prime} \vec{e} G^{\prime} T^{\prime}$

When we start on $(n+1, n+1)$, trace back the path.
We let two path both trace back to the point $(n-j+1, n-j+1)$, in the next step, the path in Figure 2.3 is below the diagonal $y=x$, but the path in Figure 2.4 is still above the diagonal $y=x$.

This is a contradiction, as two paths are the same.


Figure 2.5: $Q \vec{e} G T$

When we start on $(n+1, n+1)$, trace back the path.
We let two paths both trace back to the point $(n-l+1, n-l+1)$, in the next step, the path in Figure 2.6 is below the diagonal $y=x$, but the path in Figure 2.5 is still above diagonal $y=x$.

This is a contradiction, as two paths are the same.
Thus, we have proved that $l=j$.
$\therefore T=T^{\prime}$.
Claim: $G=G^{\prime}$.
Case1: $i>k$


Figure 2.7: $Q \vec{e} G T$
Figure 2.8: $Q^{\prime} \vec{e} G^{\prime} T^{\prime}$

We both start on $(n-j+1, n-j)$.
Since $i>k$, when we let the path in Figure 2.8 trace back to $(n-j-k+1, n-j-k)$, the next segment is $\vec{e}$, but the path in Figure 2.7 is not $\vec{e}$.

This is a contradiction, as two paths are the same.
Case2: $i<k$


Figure 2.9: $Q^{\prime} \vec{e} G^{\prime} T^{\prime}$

We both start on $(n-j+1, n-j)$.
Since $i<k$, when we let the path in Figure 2.10 trace back to $(n-j-i+1, n-j-i)$, the next segment is not $\vec{e}$, but the path in Figure 2.9 is $\vec{e}$.

This is a contradiction, as two paths are the same.
Thus, we have proved that $i=k$.
$\therefore G=G^{\prime}$.
Since $T=T^{\prime}$ and $G=G^{\prime}$.
$\because Q \vec{e} G T=Q^{\prime} \vec{e} G^{\prime} T^{\prime} \Rightarrow Q \vec{e}=Q^{\prime} \vec{e}$
$\therefore Q=Q^{\prime} \Rightarrow G T \vec{e} Q=G^{\prime} T^{\prime} \stackrel{\rightharpoonup}{e} Q^{\prime}$
$\therefore f_{1}$ is one-to one.
Claim: $f_{1}$ is onto.
i.e. For any path in $Y_{1}$, which has at most $n$ flaws, we choose the last east leaving the diagonal $y=x$, denoted by $\hat{e}$, then we switch the portions before $\hat{e}$ and after $\hat{e}$. We can get a new path with at least one flaw, and the path is in $X_{1}$.

To show by graph:


Figure 2.11: RêS $\xrightarrow{\text { preimage under } f_{1}}$ SêR

To show by formula:
$Q=R \hat{e} S \xrightarrow{\text { preimage under } f_{1}} S \hat{e} R=P$,
where $Q$ has at most $n$ flaws, $P$ has at least one flaw.
In fact, if $Q$ has $k$ flaws, $P$ has $k+1$ flaws.
So, for every path $Q$ in $Y_{1}$, we can find a path $P$ in $X_{1}$ such that $f_{1}(P)=Q$.
Therefore, $f_{1}$ is one-to-one and onto.

NOTE: Let $f_{1}^{-1}$ be the inverse function of $f_{1}$.

Lemma 2.3. The first east $\stackrel{\rightharpoonup}{e}$ touching the diagonal $y=x$ in $X_{1}$ is below the diagonal $y=x$ in $Y_{1}$ after using $f_{1}$.

Proof. Let $P=S \vec{e} R$, where $S$ is a $(j, j+1)$ path, $\vec{e}$ is a $(1,0)$ east path, and $R$ is an $(n-$ $j, n-j)$ path.

After using $f_{1}$, we swap $R$ and $S$, since $R$ is an $(n-j, n-j)$ path, the next segment $\vec{e}$ is below the diagonal $y=x$.
Thus, we have proved that the first east $\vec{e}$ touching the diagonal $y=x$ in $X_{1}$ and it is below the
diagonal $y=x$ in $Y_{1}$ after using $f_{1}$.

Lemma 2.4. The last east $\hat{e}$ leaving from diagonal $y=x$ in $Y_{1}$ is the first east $\vec{e}$ touching the diagonal $y=x$ in $X_{1}$.
i.e. If $\vec{e}$ is the first east touching the diagonal $y=x$ in $X_{1}$, then $\vec{e}$ is the last east leaving the diagonal $y=x$ in $Y_{1}$.


Figure 2.12: Lemma2. 4

Proof. Since $\vec{e}$ is the first east touching the diagonal $y=x$, we can observe that there is a empty area enclosed by the first north that leaves the diagonal $y=x$, denoted by $\vec{n}$, the diagonal $y=x$, $e$, and the diagonal $y=x+1$.
After swapping two portions, another empty is enclosed by $\vec{e}$, the diagonal $y=x, \vec{n}$, and the diagonal $y=x-1$, so that there is no east segment can touch the diagonal $y=x$ between $\vec{e}$ and $\vec{n}$.

And the remain segments which are behind $\vec{n}$ are at most touching the diagonal $y=x$ but not be below the diagonal $y=x$. Therefore, the last east $\hat{e}$ leaving from diagonal $y=x$ in $Y_{1}$ is the first east $\vec{e}$ touching the diagonal $y=x$ in $X_{1}$.

Definition 2.5. The set $A_{1}$ consists of all paths which first segment is north, and the first touching the diagonal $y=x$ east is marked.

The set $B_{1}$ consists of all paths which are good path.

Define $g_{1}$ from $A_{1}$ into $B_{1}$ by $g_{1}(P)=f_{1}^{(k)}(P)$, where $P$ has $k$ flaws, and $f_{1}^{(k)}=\underbrace{f_{1} \circ f_{1} \circ \ldots \circ f_{1}}_{k}$.

Example 2.6. The following example is one of $g_{1}(P)$ :


Figure 2.13: $n=3$

Lemma 2.7. In $g_{1}(P)$, after using the first $f_{1}$, the first east which is denoted by $\vec{e}$, connects with the first segment of $P$ in $A_{1}$. And this part will not be separated afterward.

Proof. First, we prove the first part.
Since using $f_{1}$ will swap the portion berfore and after $\vec{e}$, and the first segment of path is north, after using $f_{1}, \vec{e}$ connects with the north segment.

Thus, we have proved.

Next, we prove the second part.
Notice that after using the first $f_{1}$, the part of $\vec{e}$ and the north segment is below the diagonal $y=x$.

There is another first touching the diagonal $y=x$ east, and the part is in a $(j, j)$ path after that east, in the next step, we use $f_{1}$ again, so this part will be swapped to before that east, since it is $(j, j)$ path, the part is still below the diagonal $y=x$.
Therefore, no matter how many times we use $f_{1}, \vec{e}$ connects with the first segment of $P$ in $A_{1}$ and they are not be separated afterward.

Theorem 2.8. $g_{1}$ is one-to-one and onto.

Proof. Claim: $g_{1}$ is one-to-one.
$g_{1}(P)=g_{1}(Q) \Rightarrow f_{1}^{(k)}(P)=f_{1}^{(h)}(Q)$, where $P$ has $k$ flaws and $Q$ has $h$ flaws.
Case1: $k<h$
$f_{1}^{(k)}(P)=f_{1}^{(h)}(Q) \Rightarrow f_{1}\left(f_{1}^{(k-1)}(P)\right)=f_{1}\left(f_{1}^{(h-1)}(Q)\right)$
$\because f_{1}$ is one-to-one.
$\therefore f_{1}^{(k-1)}(P)=f_{1}^{(h-1)}(Q)$.
$f_{1}\left(f_{1}^{(k-2)}(P)\right)=f_{1}\left(f_{1}^{(h-2)}(Q)\right) \Rightarrow f_{1}^{(k-2)}(P)=f_{1}^{(h-2)}(Q)$, since $f_{1}$ is one-to-one.
Use this way for $k-1$ times, we have $f_{1}(P)=f_{1}^{(h-(k-1))}(Q)=f_{1}\left(f_{1}^{(h-k)}(Q)\right)$
$\Rightarrow P=f_{1}^{(h-k)}(Q)$
The first $\vec{e}$ of $P$ is above the diagonal $y=x$, but the first $\vec{e}$ of $f_{1}^{(h-k)}(Q)$ is below the diagonal $y=x$ by Lemma 2.7.

This is a contradiction.
Case2: $k>h_{1}$
$f_{1}^{(k)}(P)=f_{1}^{(h)}(Q) \Rightarrow f_{1}\left(f_{1}^{(k-1)}(P)\right)=f_{1}\left(f_{1}^{(h-1)}(Q)\right)$
$\because f_{1}$ is one-to-one.
$\therefore f_{1}^{(k-1)}(P)=f_{1}^{(h-1)}(Q)$.
$f_{1}\left(f_{1}^{(k-2)}(P)\right)=f_{1}\left(f_{1}^{(h-2)}(Q)\right) \Rightarrow / f_{1}^{(k-2)}(P)=f_{1}^{(h-2)}(Q)$, since $f_{1}$ is one-to-one.
Use this way for $h-1$ times, we have $f_{1}^{(k-(h-1))}(P)=f_{1}\left(f_{1}^{(k-h)}(P)\right)=f_{1}(Q)$
$\Rightarrow f_{1}^{(k-h)}(P)=Q$
The first $\vec{e}$ of $Q$ is above the diagonal $y=x$, but the first $\vec{e}$ of $f_{1}^{(k-h)}(P)$ is below the diagonal $y=x$ by Lemma 2.7.

This is a contradiction.
Case3: $k=h$
$f_{1}^{(k)}(P)=f_{1}^{(h)}(Q) \Rightarrow f_{1}\left(f_{1}^{(k-1)}(P)\right)=f_{1}\left(f_{1}^{(h-1)}(Q)\right)$
$\Rightarrow f_{1}^{(k-1)}(P)=f_{1}^{(h-1)}(Q)\left(\because f_{1}\right.$ is one-to-one. $)$
Use this way for $k-1$ times, we have $f_{1}(P)=f_{1}(Q) \Rightarrow P=Q$
Therefore, $g_{1}$ is one-to-one.

Claim: $g_{1}$ is onto.
Given $Q \in B_{1}$.
Define $f_{1}^{(-k)}=\underbrace{f_{1}^{-1} \circ f_{1}^{-1} \circ \ldots \circ f_{1}^{-1}}_{k}$.
$f_{1}^{-1}(Q)$ is a preimage of $Q$ under $f_{1}$ and $f_{1}^{-1}(Q)$ has 1 flaw.
We can use this way for $n+1$ times, until the segment $\vec{e}$ is above the diagonal $y=x$ by Lemma
2.7.

So we have $f_{1}^{-(n+1)}(Q)=P$, where $P$ has $n+1$ flaws, $P \in A_{1}$.
Thus, $g_{1}$ is onto. Therefore, $g_{1}$ is one-to-one and onto.

Definition 2.9. The set $C_{1}$ consists of all $(n, n)$ paths which are replaced the marked east and the next north segment in $B_{1}$ with a dot, and all paths in $B_{1}$ are $(n+1, n+1)$ path.

Let $h_{1}$ be the function from $B_{1}$ into $C_{1}$.
i.e. $P=R \vec{e} \vec{n} S$ is an $(n+1, n+1)$ path, where $R$ and $S$ are all good paths.
$h_{1}(P)=h_{1}(R \vec{e} \vec{n} S)=R \bullet S$

Theorem 2.10. $h_{1}$ is one-to-one and onto.

Proof. It is clearly obvious that $h_{1}$ is one-to-one and onto.
Given $Q=R \bullet S \in C_{1}$.
We can change $\bullet$ into $\vec{e} \vec{n}$.
Thus, $R \bullet S \Rightarrow R \vec{e} \vec{n} S \in B_{1}$.
Therefore, $h_{1}$ is one-to-one and onto.

## Chapter 3

## Paths Start with East

Definition 3.1. The set $X_{2}$ consists of all $(n+1, n+1)$ paths which have at most $n$ flaw.
Each path in $X_{2}$ can be factorized into $T G \vec{n} Q$. The set $Y_{2}$ consists of all $(n+1, n+1)$ paths which has at least one flaws.

Define a function $f_{2}$ from $X_{2}$ into $Y_{2}$ by the following:

1. Starting from the bottom left, $(0,0)$, follow the path until it first travels below the diagonal $y=x$.
2. Continue to follow the path until it touches the diagonal $y=x$ again. Denote by $\vec{n}$, the first such segment that touches the diagonal $y=x$, in fact, $\vec{n}$ must be an north segment.
3. Swap the portion of the path before $\stackrel{\rightharpoonup}{n}$ with portion after $\stackrel{\rightharpoonup}{n}$.
i.e. $f_{2}(T G \vec{n} Q)=Q \stackrel{\rightharpoonup}{n} T G$,
where $T$ is an $(i, i)$ totally bad path, $0 \leq i \leq n+1, G$ is a $(j+1, j)$ good path, $0 \leq j \leq n-i$, the north segment $\stackrel{\rightharpoonup}{n}$ is the first north touching diagonal $y=x$, and $Q$ is an $(n-i-j, n-i-j)$ path.

NOTE: After using $f_{2}$, the flaws of path $P$ increase one.
i.e. if $P$ has k flaws, $k \leq n$, then $f_{2}(P)$ has $k+1$ flaws.

To show $f_{2}(T G \vec{n} Q)=Q \stackrel{\rightharpoonup}{n} T G$ by graph, we have:


Fix $\vec{n}$ and switch $T G$ with $Q$, we have:
Figure 3.1: $T G \vec{n} Q$


Figure 3.2: $Q \vec{n} T G$

Theorem 3.2. Let $P=T G \vec{n} Q$ is an $(n+1, n+1)$ path. Define $f_{2}: X_{2} \longrightarrow Y_{2}$
by $f_{2}(T G \vec{n} Q)=Q \vec{n} T G$, where $T$ is an $(i, i)$ totally bad path, $0 \leq i \leq n+1, G$ is $a(j+1, j)$ good path, $0 \leq j \leq n-i$, the north segment $\vec{n}$ is the first north which touches the diagonal $y=x$, and $Q$ is an $(n-i-j, n-i-j)$ path. The function $f_{2}$ is one-to-one and onto.

Proof. Claim: $f_{2}$ is one-to-one.
Let $P=T G \stackrel{\rightharpoonup}{n} Q, P^{\prime}=T^{\prime} G^{\prime} \stackrel{\rightharpoonup}{n} Q^{\prime}$, where $G^{\prime}$ is a an $(l+1, l)$ good path, $T^{\prime}$ is a $(k, k)$ totally bad path, and $Q^{\prime}$ is an $(n-k-l, n-k-l)$ path.
If $f_{2}(T G \stackrel{\rightharpoonup}{n} Q)=f_{2}\left(T^{\prime} G^{\prime} \stackrel{\rightharpoonup}{n} Q^{\prime}\right) \Rightarrow Q \stackrel{\rightharpoonup}{n} T G=Q^{\prime} \stackrel{\rightharpoonup}{n} T^{\prime} G^{\prime}$.
Claim: $G=G^{\prime}$.
Casel: $l>j$


Figure 3.3: $Q \vec{n} T G$


Figure 3.4: $Q^{\prime} \vec{n} T^{\prime} G^{\prime}$

When we start on $(n+1, n+1)$, trace back the path.
We let two paths both trace back to the point $(n-j, n-j+1)$, in the next step, the path in Figure 3.3 is above the diagonal $y=x$, but the path in Figure 3.4 is still below diagonal $y=x$.

This is a contradiction, as two paths are the same.

Case2: $l<j$


Figure 3.5: $Q^{\prime} \vec{n} T^{\prime} G^{\prime}$

When we start on $(n+1, n+1)$, trace back the path.
Ww let two paths both trace back to the point $(n-l, n-l+1)$, in the next step, the path in
Figure 3.5 is above the diagonal $y=x$, but the path in Figure 3.6 is still below diagonal $y=x$.
This is a contradiction, as two paths are the same.
Thus, we have proved that $l=j$.
$\therefore G=G^{\prime}$.
Claim: $T=T^{\prime}$.
Case1: $i>k$


Figure 3.7: $Q \vec{n} T G$
Figure 3.8: $Q^{\prime} \vec{n} T^{\prime} G^{\prime}$

We both start on $(n-j, n-j+1)$.
Since $i>k$, when we let the path in Figure 3.8 trace to $(n-j-k, n-j-k+1)$, the next segment is $\vec{n}$, but the path in Figure 3.7 is not $\vec{n}$.

This is a contradiction, as two paths are the same.
Case2: $i<k$


Figure 3.9: $Q \vec{n} T G$

Figure 3.10: $Q^{\prime} \vec{n} T^{\prime} G^{\prime}$

We both start on $(n-j+1, n-j)$.
Since $i<k$, when we let the path in Figure 3.10 trace back to $(n-j-i, n-j-i+1)$, the next segment is not $\vec{n}$, but the path in Figure 3.9 is $\vec{n}$,

This is a contradiction, as two paths are the same.
Thus, we have proved that $i=k$.
$\therefore T=T^{\prime}$.
Since $G=G^{\prime}$ and $T=T^{\prime}$.
$\because Q \stackrel{\rightharpoonup}{n} T G=Q^{\prime} \stackrel{\rightharpoonup}{n} T^{\prime} G^{\prime} \Rightarrow Q \vec{n}=Q^{\prime} \vec{n}$
$\therefore Q=Q^{\prime} \Rightarrow T G \stackrel{\rightharpoonup}{n} Q=T^{\prime} G^{\prime} \stackrel{\rightharpoonup}{n} Q^{\prime}$
$\therefore f_{2}$ is one-to one.
Claim: $f_{2}$ is onto.
i.e. For any path in $Y_{2}$, which has at least one flaw, we choose the last north leaving the diagonal $y=x$, denoted by $\hat{n}$, then we switch the portions before $\hat{n}$ and after $\hat{n}$. We can get a new path with at most $n$ flaws which is in $X_{2}$.

To show by graph:


Figure 3.11: Rn̂S $\xrightarrow{\text { preimage under } f_{2}} S \hat{n} R$

To show by formula:
$Q=R \hat{n} S \xrightarrow{\text { preimage under } f_{2}} S \hat{n} R=P$,
where $Q$ has at least one flaw, $P$ has at most $n$ flaws.
In fact, if $Q$ has $k$ flaws, $P$ has $k-1$ flaws.
So, for every path $Q$ in $Y_{2}$, we can find a path $P$ in $X_{2}$ such that $f_{2}(P)=Q$.
Therefore, $f_{2}$ is one-to-one and onto.

Lemma 3.3. The first north $\vec{n}$ touching the diagonal $y=x$ in $X_{2}$ is above the diagonal $y=x$ in $Y_{2}$ after using $f_{2}$.

Proof. Let $P=S \vec{n} R$, where $S$ is a $(j+1, j)$ path, $\vec{n}$ is a $(0,1)$ north path, and $R$ is an $(n-$ $j, n-j)$ path.
After using $f_{2}$, we swap $R$ and $S$, since $R$ is an $(n-j, n-j)$ path, the next segment $\vec{n}$ is above the diagonal $y=x$.
Thus, we have proved that the first north $\vec{n}$ touching the diagonal $y=x$ in $X_{2}$ and it is above the diagonal $y=x$ in $Y_{2}$ after using $f_{2}$.

Lemma 3.4. The last north $\hat{n}$ leaving from diagonal $y=x$ in $Y_{2}$ is the first north $\vec{n}$ touching the diagonal $y=x$ in $X_{2}$.
i.e. If $\vec{n}$ is the first north touching the diagonal $y=x$ in $X_{2}$, then $\stackrel{\rightharpoonup}{n}$ is the last north leaving the diagonal $y=x$ in $Y_{2}$.


Figure 3.12: Lemma3.7 2nd part

Proof. Since $\vec{n}$ is the first north touching the diagonal $y=x$, we can observe that there is a empty area enclosed by the first east that leaves the diagonal $y=x$, denoted by $\vec{e}$, the diagonal $y=x, \vec{n}$, and the diagonal $y=x-1$.
After swapping two portions, another empty area is enclosed by $\vec{n}$, the diagonal $y=x, \vec{e}$, and the diagonal $y=x+1$, so that there is no north segment can touch the diagonal $y=x$ between $\vec{n}$ and $\vec{e}$.

And the remain segments which are behind $\vec{e}$ are at most touching the diagonal $y=x$ but not be above the diagonal $y=x$. Therefore, the last north $\hat{n}$ leaving from diagonal $y=x$ in $Y^{\text {; }}$ is the first north $\vec{n}$ touching the diagonal $y=x$ in $Y_{2}$.

Definition 3.5. The set $A_{2}$ consists of all paths which first segment is east, and the first touching the diagonal $y=x$ north is marked.

The set $B_{2}$ consists of all paths which are totally bad path.
Define $g_{2}$ from $A_{2}$ into $B_{2}$ by $g_{2}(P)=f^{(k)}(P)$, where $P$ has $k$ flaws, and $f^{(k)}=\underbrace{f_{2} \circ f_{2} \circ \ldots \circ f_{2}}_{k}$.

Example 3.6. The following example is one of $g_{2}(P)$ :


Figure 3.13: $n=3$

Lemma 3.7. In $g_{2}(P)$, after using the first $f_{2}$, the first north which is denoted by $\vec{n}$, connects with the first segment of $P$ in $A_{2}$. And this part will not be separated afterward.

Proof. First, we prove the first part.
Since using $f_{2}$ will swap the portion berfore and after $\vec{n}$, and the first segment of path is east, after using $f_{2}, \vec{n}$ connects with the east segment.

Thus, we have proved.

Then we prove the second part.
Notice that after using the first $f_{2}$, the part of $\vec{n}$ and the east segment is above the diagonal $y=x$.

There is another first touching the diagonal $y=x$ north, and the part is in a $(j, j)$ path after that north, in the next step, we use $f_{2}$ again, so this part will be swapped to before that north and since it is $(j, j)$ path, the part is still above the diagonal $y=x$.
Therefore, no matter how many times you use $f_{2}, \vec{n}$ connects with the first segment of $P$ in $A_{2}$ and they are not be separated afterward.

Theorem 3.8. $g_{2}$ is one-to-one and onto.
Proof. Claim: $g_{2}$ is one-to-one.
$g_{2}(P)=g_{2}(Q) \Rightarrow f_{2}^{(k)}(P)=f_{2}^{(h)}(Q)$, where $P$ has $k$ flaws and $Q$ has $h$ flaws.

Case1: $k<h$
$f_{2}^{(k)}(P)=f_{2}^{(h)}(Q) \Rightarrow f_{2}\left(f_{2}^{(k-1)}(P)\right)=f_{2}\left(f_{2}^{(h-1)}(Q)\right)$
$\because f_{2}$ is one-to-one.
$\therefore f_{2}^{(k-1)}(P)=f_{2}^{(h-1)}(Q)$.
$f_{2}\left(f_{2}^{(k-2)}(P)\right)=f_{2}\left(f_{2}^{(h-2)}(Q)\right) \Rightarrow f_{2}^{2(k-2)}(P)=f_{2}^{(h-2)}(Q)$. Since $f_{2}$ is one-to-one.
Use this way for $k-1$ times, we have $f_{2}(P)=f_{2}^{(h-(k-1))}(Q)=f_{2}\left(f_{2}^{(h-k)}(Q)\right)$
$\Rightarrow P=f_{2}^{(h-k)}(Q)$
The first $\vec{n}$ of $P$ is below the diagonal $y=x$, but the first $\vec{n}$ of $f_{2}^{(h-k)}(Q)$ is above the diagonal $y=x$ by Lemma 3.7.

This is a contradiction.
Case2: $k>h$
$f_{2}^{(k)}(P)=f_{2}^{(h)}(Q) \Rightarrow f_{2}\left(f_{2}^{(k-1)}(P)\right)=f_{2}\left(f_{2}^{(h-1)}(Q)\right)$
$\because f_{2}$ is one-to-one.
$\therefore f_{2}^{(k-1)}(P)=f_{2}^{(h-1)}(Q)$.
$f_{2}\left(f_{2}^{(k-2)}(P)\right)=f_{2}\left(f_{2}^{(h-2)}(Q)\right) \Rightarrow f_{2}^{(k-2)}(P)=f_{2}^{(h-2)}(Q)$. Since $f_{2}$ is one-to-one.
Use this way for $h-1$ times, we have $f_{2}^{(k-(h-1))}(P)=f_{2}\left(f_{2}^{(k-h)}(P)\right)=f_{2}(Q)$
$\Rightarrow f_{2}^{(k-h)}(P)=Q$
The first $\vec{n}$ of $Q$ is below the diagonal $y=x$, but the first $\vec{n}$ of $f_{2}^{(k-h)}(P)$ is above the diagonal $y=x$ by Lemma 3.7.

This is a contradiction.
Case3: $k=h$
$f_{2}^{(k)}(P)=f_{2}^{(h)}(Q) \Rightarrow f_{2}\left(f_{2}^{(k-1)}(P)\right)=f_{2}\left(f_{2}^{(h-1)}(Q)\right)$
$\Rightarrow f_{2}^{(k-1)}(P)=f_{2}^{(h-1)}(Q)\left(\because f_{2}\right.$ is one-to-one. $)$
Use this way for $k-1$ times, we have $f_{2}(P)=f_{2}(Q) \Rightarrow P=Q$
Therefore, $g_{2}$ is one-to-one.
Claim: $g_{2}$ is onto.
Given $Q \in B_{2}$.
Define $f_{2}^{(-k)}=\underbrace{f_{2}^{-1} \circ f_{2}^{-1} \circ \ldots \circ f_{2}^{-1}}_{k}$.

Since $f_{2}^{-1}(Q)$ is a preimage of $Q$ under $f_{2}$ and $f_{2}^{-1}(Q)$ has $n-1$ flaw.
We can use this way for $n+1$ times, until the segment $\vec{n}$ is below the diagonal $y=x$ by Lemma 3.7.

So we have $f_{2}^{-(n+1)}(Q)=P$, where $P$ has no flaw, $P \in A_{2}$.
Thus, $g_{2}$ is onto. Therefore, $g_{2}$ is one-to-one and onto.

Definition 3.9. The set $C_{2}$ consists of all $(n, n)$ paths which are replaced the marked north and the next east segment in $B_{2}$ with a dot, and all paths in $B_{2}$ are $(n+1, n+1)$ path.

Let $h_{2}$ be the function from $B_{2}$ into $C_{2}$.
i.e. $P=R \vec{n} \vec{e} S$ is an $(n+1, n+1)$ path, where $R$ and $S$ are all totally bad paths.
$h_{2}(P)=h_{2}(R \vec{n} \vec{e} S)=R \bullet S$

Theorem 3.10. $h_{2}$ is one-to-one and onto.

Proof. It is clearly obvious that $h_{2}$ is one-to-one and onto.
Given $Q=R \bullet S \in C_{2}$.
We can change $\bullet$ into $\vec{n} \vec{e}$.
Thus, $R \bullet S \Rightarrow R \vec{n} \vec{e} S \in B_{2}$.
Therefore, $h_{2}$ is one-to-one and onto.

## Chapter 4

## Summary

## 政 治

In this thesis, we prove the Catalan identity in a combinatorial way. We split the paths into two portions according to the first segment. Then we construct the functions in $A_{1} \xrightarrow{g_{1}} B_{1} \xrightarrow{h_{1}} C_{1}$ which the first segment is north.


Figure 4.1: $A_{1} \xrightarrow{g_{1}} B_{1} \xrightarrow{h_{1}} C_{1}$

And the other functions in $A_{2} \xrightarrow{g_{2}} B_{2} \xrightarrow{h_{2}} C_{2}$ which the first segment is east.


Figure 4.2: $A_{2} \xrightarrow{g_{2}} B_{2} \xrightarrow{h_{2}} C_{2}$

In chapter 3, we can also use reflection along the diagonal $y=x$ to prove the paths with east segment, since the paths in chapter 3 is reflection along the diagonal $y=x$ to the paths in chapter 2. But it will be less clear. In this thesis, we can obverse more details and easier to understand.


Appendix A

Some examples of Catalan identity
$(n+2) C_{n+1}=(4 n+2) C_{n}$
$n=1$

$n=2$, the first segment is north.

$n=2$, the first segment is east.


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