

6 附錄

6.1 附錄一

(3.3),(3.4) 及 (3.5) 式之推導

$$\begin{aligned}
D^2 &= \|Xa - C\|^2 + \|[Xa - l(Xab + \mathbf{1}d)] - [C - lS]\|^2 \\
&\quad + \|[Xa + l(Xab + \mathbf{1}d)] - [C + lS]\|^2 \\
&= a'X'Xa - C'Xa - a'X'C + C'C + 2a'X'C + l^2b^2a'X'Xa + 2l^2bda'X'\mathbf{1} \\
&\quad - 2l^2ba'X'S + 2l^2bd\mathbf{1}'Xa + 2l^2d^2\mathbf{1}'\mathbf{1} - 2l^2d\mathbf{1}'S \\
&\quad - 2C'Xa + 2C'C - 2l^2bS'Xa - 2l^2S'd\mathbf{1} + 2l^2S'S \\
&= 3a'X'Xa - 6C'Xa + 3C'C + 2l^2b^2a'X'Xa + 4l^2bda'X'\mathbf{1} - 4l^2ba'X'S \\
&\quad + 2l^2nd^2 - 4l^2dn\bar{S} + 2l^2S'S
\end{aligned}$$

令 $\frac{\partial D^2}{\partial a} = 0, \frac{\partial D^2}{\partial b} = 0, \frac{\partial D^2}{\partial d} = 0$ 得到

$$\frac{\partial D^2}{\partial a} = 3X'Xa - 3X'C + 2l^2b^2X'Xa + 2l^2bdX'\mathbf{1} - 2l^2bX'S = 0 \quad (6.1)$$

$$\frac{\partial D^2}{\partial b} = ba'X'Xa + da'X'\mathbf{1} - a'X'S = 0 \quad (6.2)$$

$$\frac{\partial D^2}{\partial d} = ba'X'\mathbf{1} + nd - \mathbf{1}'S = 0 \quad (6.3)$$

由(6.1)知 $a = \frac{1}{3+2l^2b^2}(X'X)^{-1}[3X'C + 2l^2bX'S - 2l^2bdX'\mathbf{1}]$ ，將 a 之值代入(6.2)與(6.3)中，可得

$$\begin{aligned}
\frac{\partial D^2}{\partial b} &= 9b\|\hat{C}\|^2 + 6l^2b^2\hat{C}'S - 6l^2b^2dn\bar{C} + 9n\bar{C}d \\
&\quad + 12l^2n\bar{S}bd - 6l^2nbd^2 - 9C'\hat{S} - 6l^2\|\hat{S}\|^2b
\end{aligned} \quad (6.4)$$

$$\frac{\partial D^2}{\partial d} = b\bar{C} + d - \bar{S} = 0 \quad (6.5)$$

其中 $X(X'X)^{-1}X'C = \hat{C}, X(X'X)^{-1}X'S = \hat{S}, \bar{\hat{S}} = \bar{S}$ 。

再由(6.5)式中得知 $d = \bar{S} - b\bar{C}$ ，代入(6.4)中可以簡化成一個 b 的二次式

$$K_1b^2 + K_2b + K_3 = 0$$

故可得 $\hat{b} = \frac{-K_1 \pm \sqrt{K_2^2 - 4K_1K_3}}{2K_1}$

6.2 附錄二

(4.2),(4.3),(4.4) 公式之推導

簡單距離公式下：

$$e_{(i)}^2 = (c_i - x_i \hat{a}_{(i)})^2 + (s_i - x_i \hat{r}_{(i)})^2$$

因 $\hat{a}_{(i)} = \hat{a} - \frac{e_i^c}{1-h_{ii}}(X'X)^{-1}x_i'$ ，且 $\hat{r}_{(i)} = \hat{r} - \frac{e_i^s}{1-h_{ii}}(X'X)^{-1}x_i'$ ，故

$$\begin{aligned} e_{(i)}^2 &= (c_i - x_i \hat{a} + \frac{e_i^c}{1-h_{ii}}x_i(X'X)^{-1}x_i')^2 + \\ &\quad (s_i - x_i \hat{r} + \frac{e_i^s}{1-h_{ii}}x_i(X'X)^{-1}x_i')^2 \\ &= (\frac{e_i^c}{1-h_{ii}})^2 + (\frac{e_i^s}{1-h_{ii}})^2 \\ &= (\frac{e_i}{1-h_{ii}})^2 \end{aligned}$$

Yang 和 Ko 距離公式下：

$$\begin{aligned} e_i^2 &= (c_i - x_i \hat{a})^2 + ((c_i - ls_i) - (x_i \hat{a} - lx_i \hat{r}))^2 + \\ &\quad ((c_i + ls_i) - (x_i \hat{a} + lx_i \hat{r}))^2 \\ &= 3(c_i - x_i \hat{a})^2 + 2(l(s_i - x_i \hat{r}))^2 \\ &= 3(e_i^c)^2 + 2l^2(e_i^s)^2 \end{aligned}$$

$$\begin{aligned} e_{(i)}^2 &= (c_i - x_i \hat{a}_{(i)})^2 + ((c_i - ls_i) - (x_i \hat{a}_{(i)} - lx_i' \hat{r}_{(i)}))^2 + \\ &\quad ((c_i + ls_i) - (x_i' \hat{a}_{(i)} + lx_i' \hat{r}_{(i)}))^2 \\ &= 3(c_i - x_i \hat{a}_{(i)})^2 + 2(ls_i - l(x_i \hat{r}_{(i)}))^2 \\ &= 3(\frac{e_i^c}{1-h_{ii}})^2 + 2l^2(\frac{e_i^s}{1-h_{ii}})^2 \\ &= (\frac{e_i}{1-h_{ii}})^2 \end{aligned}$$

6.3 附錄三

引理 4.1 之證明

證明：欲證明 \tilde{d}_{LR} 為距離測度，即需證明以下三性質成立：

1. $\forall \mathbb{X}, \mathbb{Y} \in \tilde{F}_{LR}(\mathfrak{R}), \tilde{d}_{LR}(\mathbb{X}, \mathbb{Y}) \geq 0$, 如果 $\tilde{d}_{LR}(\mathbb{X}, \mathbb{Y}) = 0$ 則 $\mathbb{X} = \mathbb{Y}$ 。
2. $\forall \mathbb{X}, \mathbb{Y} \in \tilde{F}_{LR}(\mathfrak{R}), \tilde{d}_{LR}(\mathbb{X}, \mathbb{Y}) = \tilde{d}_{LR}(\mathbb{Y}, \mathbb{X})$ 。
3. $\forall \mathbb{X}, \mathbb{Y}, \mathbb{Z} \in \tilde{F}_{LR}(\mathfrak{R}), \tilde{d}_{LR}(\mathbb{X}, \mathbb{Y}) \leq \tilde{d}_{LR}(\mathbb{X}, \mathbb{Z}) + \tilde{d}_{LR}(\mathbb{Z}, \mathbb{Y})$

因爲 d 是距離測度，可以很容易證明1和2兩性質成立，故僅需證明第3性質：

$$\begin{aligned}
\text{因 } \tilde{d}_{LR}^2(\mathbb{X}, \mathbb{Y}) &= \sum_{i=1}^p d^2(X_i, Y_i) \\
&\leq \sum_{i=1}^p d^2(X_i, Z_i) + \sum_{i=1}^p d^2(Z_i, Y_i) \\
&\leq \tilde{d}_{LR}^2(\mathbb{X}, \mathbb{Z}) + \tilde{d}_{LR}^2(\mathbb{Z}, \mathbb{Y}) + 2\sqrt{\sum_{i=1}^p d^2(X_i, Z_i)}\sqrt{\sum_{i=1}^p d^2(Z_i, Y_i)} \\
&= (\tilde{d}_{LR}(\mathbb{X}, \mathbb{Z}) + \tilde{d}_{LR}(\mathbb{Z}, \mathbb{Y}))^2 \\
\text{故 } \tilde{d}_{LR}(\mathbb{X}, \mathbb{Y}) &\leq \tilde{d}_{LR}(\mathbb{X}, \mathbb{Z}) + \tilde{d}_{LR}(\mathbb{Z}, \mathbb{Y})
\end{aligned}$$

其次，設 d 是完備距離測度。

令 $\{\mathbb{X}^m\}_{m=1}^\infty$ 是一個在 $\tilde{F}_{LR}(\mathfrak{R})$ 上的柯西數列，即

$\forall \varepsilon > 0, \exists k \in \mathbb{N} \ni m, m' > k$ 恆有 $\tilde{d}_{LR}(\mathbb{X}^m, \mathbb{X}^{m'}) < \varepsilon$ 。

則 $\forall m, m' > k, d(X_j^m, X_j^{m'}) < \sqrt{\sum_{i=1}^p d^2(X_i^m, X_i^{m'})} = \tilde{d}_{LR}(\mathbb{X}^m, \mathbb{X}^{m'}) < \varepsilon$ 。

因此 $\forall 1 \leq j \leq p, \{X_j^m\}_{m=1}^\infty$ 是一個在 $F_{LR}(\mathfrak{R})$ 上的柯西數列。

故 $\exists X_j \in F_{LR}(\mathfrak{R}), \ni X_j^m \rightarrow X_j$ 。令 $\mathbb{X} = (X_1, X_2, \dots, X_p)'$ 。

$\because X_j^m \rightarrow X_j \therefore \forall \varepsilon > 0, \exists n_j \in \mathbb{N} \ni m > n_j$ 恆有 $d(X_j^m, X_j) < \frac{\varepsilon}{\sqrt{p}}, j = 1, 2, \dots, p$ 。

令 $n = \max\{n_1, n_2, \dots, n_p\}$ ，則 $\forall m > n$ ，恆有 $\tilde{d}_{LR}(\mathbb{X}^m, \mathbb{X}) = \sqrt{\sum_{i=1}^p d^2(X_i^m, X_i)} < \varepsilon$ ，即 $\mathbb{X}^m \rightarrow \mathbb{X}$ 。

6.4 附錄四

(4.6),(4.7) 式之推導

簡單距離公式下：

$$\begin{aligned}
CD_i &= \frac{1}{ps^2} \tilde{d}_{LR}(\hat{Y}, \hat{Y}_{(i)}) \\
&= \frac{1}{ps^2} \sum_{i=1}^n d^2(\hat{Y}_i, \hat{Y}_{(i)}) \\
&= \frac{1}{ps^2} \left\{ \sum_{i=1}^n (x_i \hat{a} - x_i \hat{a}_{(i)})^2 + \sum_{i=1}^n (x_i \hat{r} - x_i \hat{r}_{(i)})^2 \right\} \\
&= \frac{1}{ps^2} \left\{ \left(\frac{e_i^c}{1 - h_{ii}} \right)^2 h_{ii} + \left(\frac{e_i^s}{1 - h_{ii}} \right)^2 h_{ii} \right\} \\
&= \frac{1}{ps^2} \frac{e_i^2 h_{ii}}{(1 - h_{ii})^2}
\end{aligned}$$

Yang 和 Ko 距離公式下：

$$\begin{aligned}
CD_i &= \frac{1}{ps^2} \tilde{d}_{LR}(\hat{Y}, \hat{Y}_{(i)}) \\
&= \frac{1}{ps^2} \sum_{i=1}^n d^2(\hat{Y}_i, \hat{Y}_{(i)}) \\
&= \frac{1}{ps^2} \left\{ \sum_{i=1}^n (x_i \hat{a} - x_i \hat{a}_{(i)})^2 + \sum_{i=1}^n ((x_i \hat{a} - lx_i \hat{r}) - (x_i \hat{a}_{(i)} - lx_i \hat{r}_{(i)}))^2 \right. \\
&\quad \left. + \sum_{i=1}^n ((x_i \hat{a} + lx_i \hat{r}) - (x_i \hat{a}_{(i)} + lx_i \hat{r}_{(i)}))^2 \right\} \\
&= \frac{1}{ps^2} \left\{ 3 \left(\frac{e_i^c}{1 - h_{ii}} \right)^2 h_{ii} + 2l^2 \left(\frac{e_i^s}{1 - h_{ii}} \right)^2 h_{ii} \right\} \\
&= \frac{1}{ps^2} \frac{e_i^2 h_{ii}}{(1 - h_{ii})^2}
\end{aligned}$$