

Bounded Tolerance Representations for Maximal Outerplanar Graphs

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ABSTRACT

A graph $G = (V, E)$ is a *tolerance graph* if there is a set $I = \{I_v | v \in V\}$ of closed real interval and a set $\tau = \{\tau_v | v \in V\}$ of positive real numbers such that $(x, y) \in E \Leftrightarrow |I_x \cap I_y| \geq \min\{\tau_x, \tau_y\}$. We show that if G is a 2-connected maximal outerplanar graph with more than two vertices of degree 2, then G has S_3 as an induced subgraph. We provide a characterization of the class of 2-connected maximal outerplanar graphs that are bounded tolerance graphs.

Keywords: Tolerance graph; Maximal outerplanar graphs; Interval graphs; 3-sun

1. Introduction

The intervals on the real line can be very useful tools. They could represent fragments of DNA on the genome, the durations of a set of events on a time line, or an estimation [4]. *Interval graphs* were introduced in graph theory. Each vertex v in an interval graph $G = (V, E)$ is associated with an interval I_v , and two vertices are adjacent in G if and only if the intersection of their associated intervals is nonempty. Tolerance graphs, introduced by Golumbic and Monma [1], are generalizations of interval graphs. An undirected graph G is a *tolerance graph* if each vertex $x \in V(G)$ can be assigned a closed interval I_x and a tolerance $t_x > 0$ such that $xy \in E(G)$ if and only if $|I_x \cap I_y| \geq \min\{t_x, t_y\}$. Such a collection (\mathcal{I}, t) of intervals and tolerances is called a *tolerance representation* of G where $\mathcal{I} = \{I_x | x \in V\}$ and $t = \{t_x | x \in V\}$. If a graph G has a tolerance representation with $t_v \leq |I_v|$ for all $v \in V$, then G is called a *bounded tolerance graph* and the representation is called a *bounded tolerance representation*.

Golumbic and Trenk [2] mentioned that their original motivation of studying tolerance graphs was the need to solve scheduling problems in which resources such

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as rooms, vehicles, support personnel, etc. may be needed on an exclusive basis, but where a measure of flexibility or tolerance would allow for sharing or relinquishing the resource if a solution is not otherwise possible. One can think of this as a model of conflicts for events occurring in a block of time, in which intervals represent a set of events on a time line and their associated tolerances are flexibility of the event. Golombic and Trenk gave characterizations of trees and bipartite graphs, respectively, which are bounded tolerance graphs.

2. A results on maximal outerplanar graphs

A graph is *outerplanar* if it has an embedding in the plane with every vertex on the boundary of the unbounded face. A *maximal outerplanar graph* is a simple outerplanar graph that is not a spanning subgraph of a larger simple outerplanar graph.

A *chord* is an edge joining two nonconsecutive vertices of a cycle. A chord in a simple maximal outerplanar graph belongs to exactly two triangles i.e., the end vertices of any chord have exactly two common neighbors. A triangle is called an *inner triangle* of G if all its three edges are chords.

There are two structures play important roles in our main result. Three vertices $v_1, v_2, v_3 \in V(G)$ form an *asteroidal triple* (AT) of graph G , if for every permutation i, j, k of $1, 2, 3$, there is a path from v_i to v_j which avoids using any vertex in the closed neighborhood $N[v_k] = \{v_k\} \cup N(v_k)$. See Figure 1 for example. The k -sun S_k ($k \geq 3$) is the graph with the vertex set $\{x_1, x_2, \dots, x_k\} \cup \{y_1, y_2, \dots, y_k\}$ and the edge set $\{x_1y_1, y_1x_2, x_2y_2, \dots, x_ky_k, y_kx_1\} \cup \{y_iy_j | i \neq j\}$. See Figure 2 for S_3 .

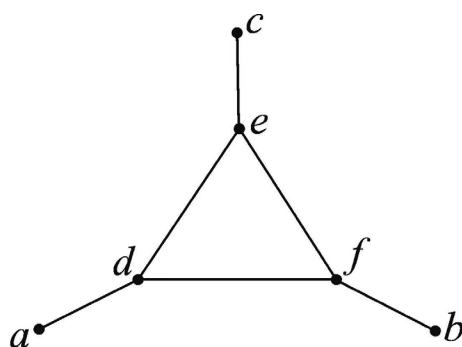


Figure 1. The set $\{a, b, c\}$ is an asteroidal triple.

Lemma 1. *Let G be a 2-connected maximal outerplanar graph. If G has more than two vertices of degree 2, then G has S_3 as an induced subgraph.*

Proof. It is sufficient to show that G has an inner triangle.

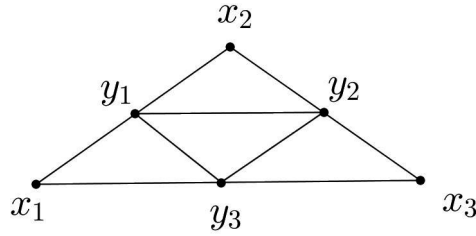


Figure 2. The graph of S_3 .

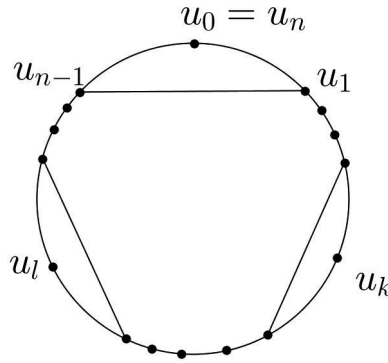


Figure 3. The graph G .

Let $u_0u_1 \dots u_n$ be the cycle which forms the boundary of the unbounded region of G . Suppose $\deg(u_0) = \deg(u_k) = \deg(u_l) = 2$, where $2 \leq k, k + 2 \leq l \leq n - 2$. See Figure 3. Let $i' = \max\{i | u_iu_j \in E(G), 1 \leq i \leq k - 1, l + 1 \leq j \leq n - 1\}$ and $j' = \min\{j | u_iu_j \in E(G), 1 \leq i \leq k - 1, l + 1 \leq j \leq n - 1\}$. Then $u_{i'}u_{j'} \in E(G)$. There exists u_p ($i' < p < j'$) which is a common neighbor of $u_{i'}$ and $u_{j'}$. We see that $k + 1 \leq p \leq l - 1$. Then $u_{i'}u_pu_{j'}$ is an inner triangle of G .

3. Main result

Let $n(G)$ denote the number of vertices of a graph G .

Theorem 1. *Suppose that G is a 2-connected maximal outerplanar graph with $n(G) \geq 4$. The following are equivalent.*

- (i) G is a bounded tolerance graph.
- (ii) G is AT-free.
- (iii) G has no induced subgraph S_3 .
- (iv) G has exactly two vertices of degree 2.
- (v) G is an interval graph.

Proof. (i) \Rightarrow (ii): Golumbic and Trenk [2] showed that bounded tolerance graphs are cocomparability graphs and Golumbic et al. [3] showed that all cocomparability graphs are AT-free. Therefore, bounded tolerance graphs are AT-free.

(ii) \Rightarrow (iii): The reason is that S_3 contains an AT. See Figure 2.

(iii) \Rightarrow (iv): By Lemma 1, G has exactly two vertices of degree 2.

(iv) \Rightarrow (v): Suppose that G has exactly two vertices of degree 2.

Let x and y be the vertices of degree 2. We have the following three cases.

Case 1: The vertices x and y have two common neighbors.

In this case, $n(G) = 4$. It is easy to show that G is an interval graph.

Case 2: The vertices x and y have exactly one common neighbor.

Let u be the common neighbor of x and y . Let v_1, v_2, \dots, v_k be vertices between x and y . Then, there is no chords of the form $v_i v_j$, otherwise it will contradict to the fact that there are only two vertices of degree 2. Therefore, all vertices v_i , $1 \leq i \leq k$ are neighbors of u . The graph G is given in Figure 4.

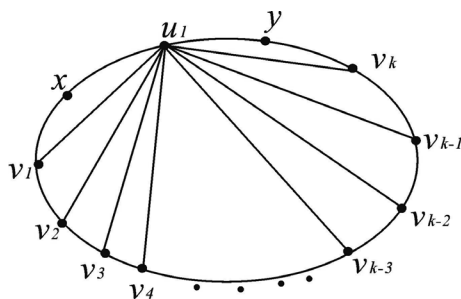


Figure 4. The graph G .

We have an interval representation of G as shown in Figure 5. Hence, G is an interval graph.

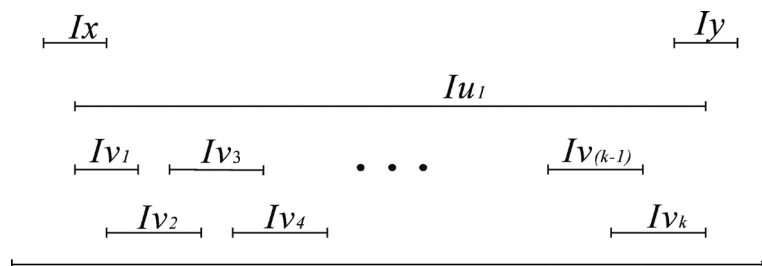


Figure 5. The interval representation of G .

Case 3: The vertices x and y have no common neighbors .

Let u_1, u_2, \dots, u_n be vertices between x and y along the boundary clockwise, and v_1, v_2, \dots, v_k be vertices between x and y along the boundary counterclockwise. Then, there is no chords of the form $v_i v_j$ and $u_i u_j$, otherwise it will contradict to the fact that there are only two vertices of degree 2.

For simplicity, we use the following examples to illustrate an interval representation of G .

Example 1: Figure 6, Figure 7.

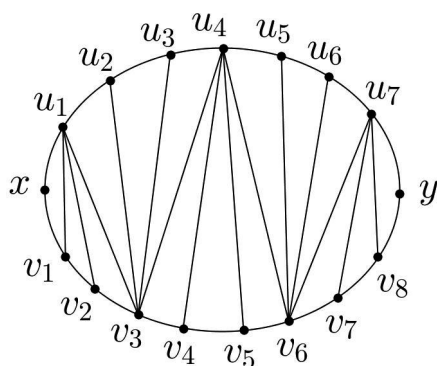


Figure 6. The graph G_1 .

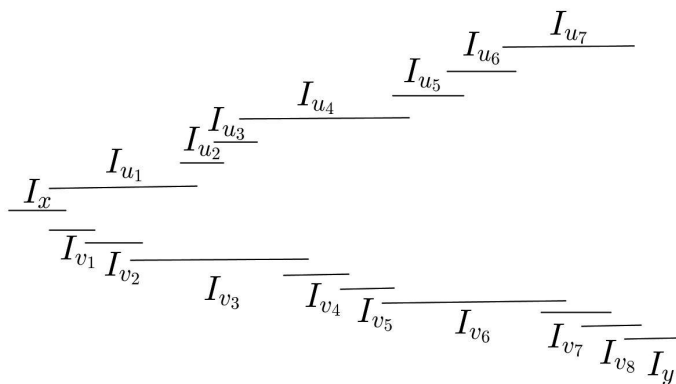


Figure 7. The interval representation of G_1 .

Example 2: Figure 8, Figure 9.

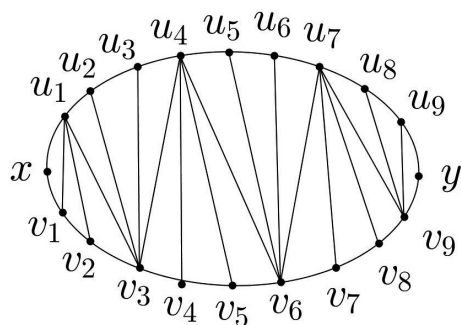


Figure 8. The graph G_2 .

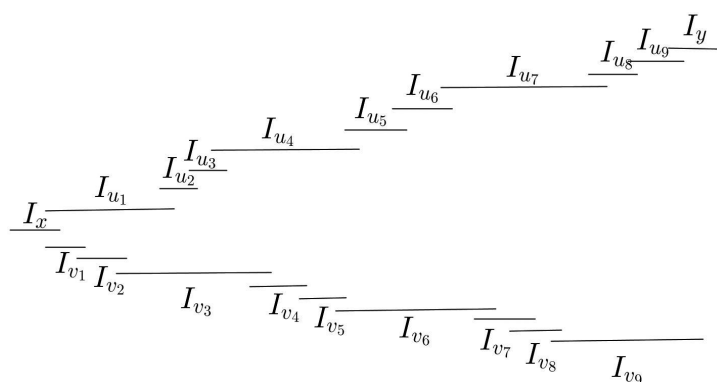


Figure 9. Interval representation of G_2 .

(v) \Rightarrow (i): The proof appears in [2] (see [2], Theorem 2.5).

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